

The JPL RL06 GRACE Gravity Solutions

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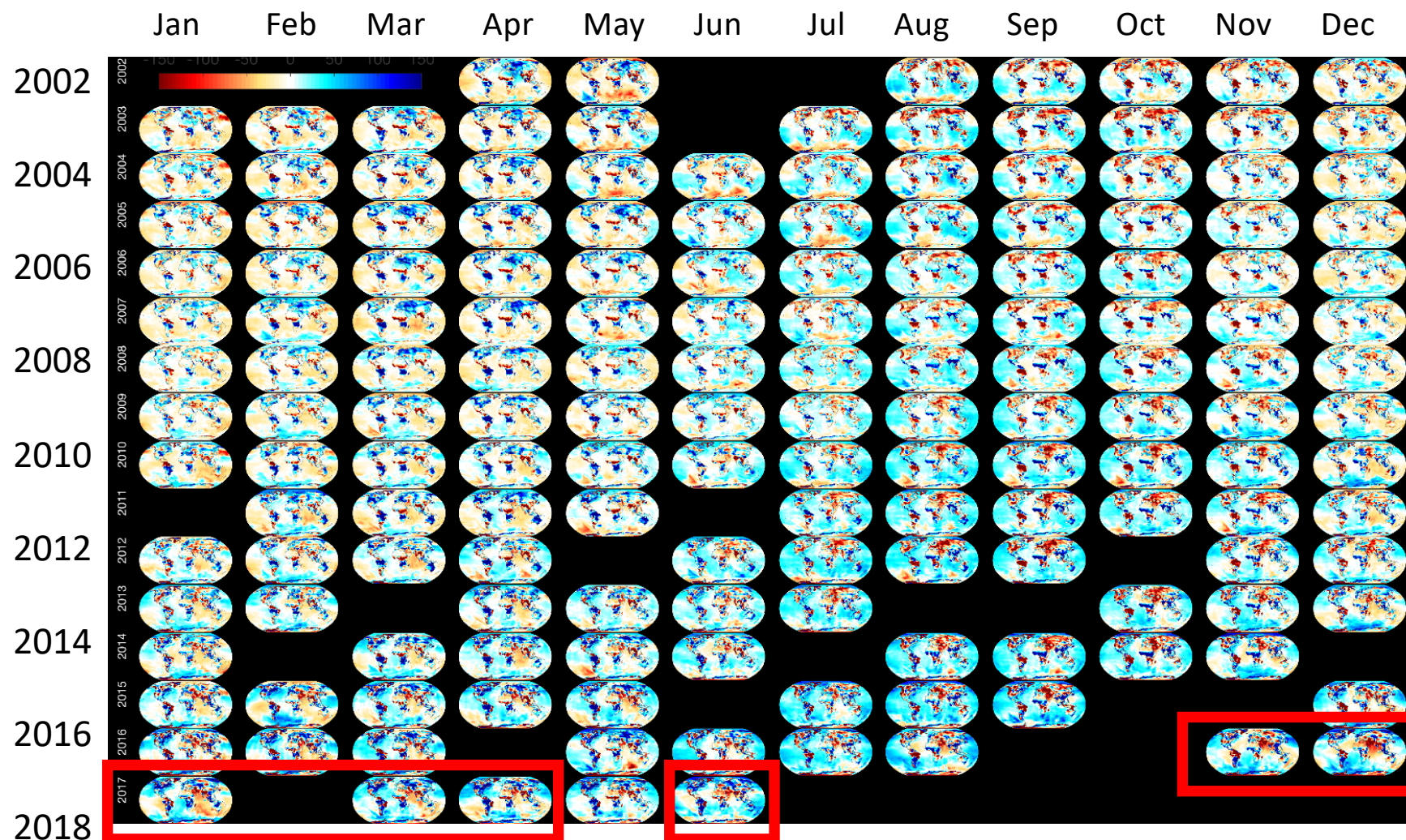
Jet Propulsion Laboratory, California Institute of Technology

October 9, 2018

GRACE / GRACE-FO Science Team Meeting

Helmholtz Centre Potsdam – GFZ German Research Centre for Geosciences
Potsdam, Germany

Data Overview



163 monthly solutions

Months with only
GRACE-A
Accelerometer Data

RL06 Data Products

- Unconstrained Monthly Spherical Harmonic Solutions
 - Ideology – attempt to do as little to the raw data as possible
 - 60 x 60
 - 96 x 96
 - 60 x 30 in months with deep repeat orbits
 - New filename definitions and YAML headers
 - April 2002 – June 2017 are released
- Constrained 3° Spherical Cap Mascon Solution
 - Ideology – retain all signals while removing as much correlated error as possible
 - Solution with Coastline Resolution Improvement (CRI) Filter
 - Solution without CRI Filter
 - Calibrated errors are provided
 - NetCDF format
 - Full timeseries is available
- Solutions can be accessed through PODAAC or GRACE Tellus (grace.jpl.nasa.gov)

Data and Parameterization



		RL05	RL06
Data Used *Only for Single Accelerometer months	Harmonics	ACC1B V02 (5-second rate) KBR1B V02 (5-second rate) SCA1B V02 (5-second rate) GPS1B V02 (300-second rate)	ACC1B V02 (5-second rate) KBR1B V03 (5-second rate) SCA1B V03 (5-second rate) GPS1B V02 (30-second rate) - downweighted *ACT1B V02 (5-second rate)
	Mascons	ACC1B V02 (5-second rate) KBR1B V02 (5-second rate) SCA1B V02 (5-second rate)	ACC1B V02 (5-second rate) KBR1B V03 (5-second rate) SCA1B V03 (5-second rate) GPS1B V02 (30-second rate) - downweighted *ACT1B V02 (5-second rate)
Parameterization *Only for Single Accelerometer months	Harmonics and Mascons	Satellite States: once per day; GPS phase biases: once per pass; KBR range-rate empirical biases/drifts/once-per-rev: 90 min; Accelerometer Biases/Rates: X and Z daily, Y is 3 hourly; *Empirical accelerations (constant, once/rev) every 90 min in alongtrack and crosstrack	Satellite States: once per day GPS phase biases: once per pass KBR range-rate empirical biases/drifts/once-per-rev: 90 min Accelerometer Biases/Rates: X and Z daily, Y is 3 hourly Full Accelerometer Scale Matrix: daily (Klinger et al., 2016) *Empirical accelerations (constant, once/rev) every 90 min in alongtrack and crosstrack

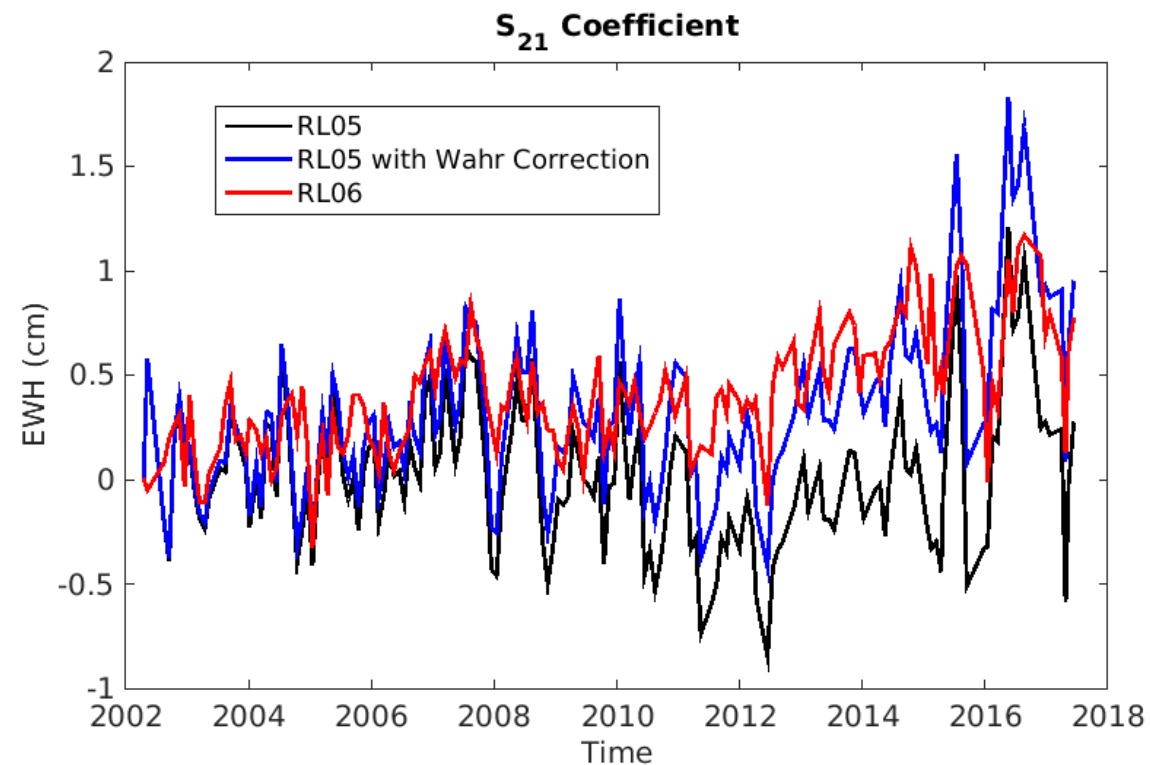
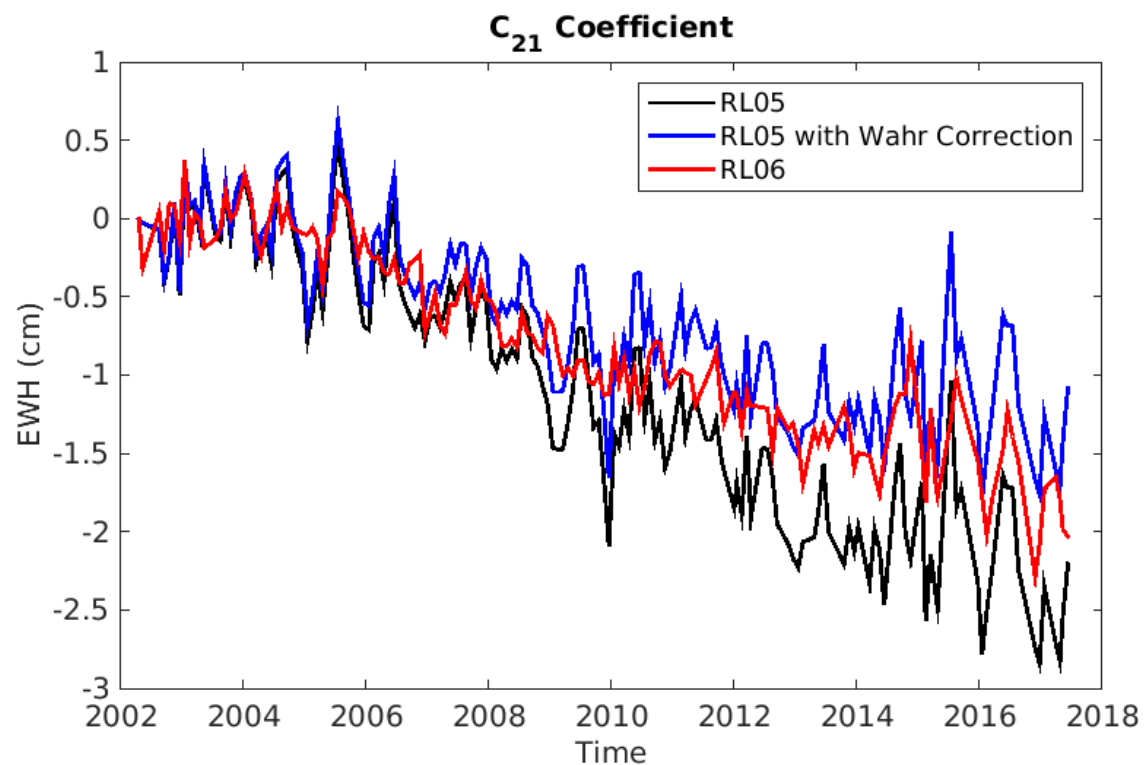
Background models



	RL05	RL06	Remarks
Static Field	gif48 180x180	ggm05c 360x360	Epoch changes from 01/07 to 01/08; earthquakes included in the static field
Atmosphere/Ocean Dealiasing Product	AOD RL05 6-hr, 100x100	AOD RL06 3-hr, 180x180	GAE, GAF, GAG products no longer needed
Ocean Tides	GOT4.7 90x90	FES2014 180x180	Changes from 90x90 to 180x180
Air Tides	Ray and Ponte, 2003	Ray and Ponte, 2003	S1 and S2, 100x100
Mean Pole	IERS2010	Linear Mean Pole (<i>Ries</i> , 2017)	Correction to C_{21}/S_{21} recommended by <i>Wahr et al.</i> (2015) is no longer needed
N-body Perturbations	DE421	DE430	

C21/S21

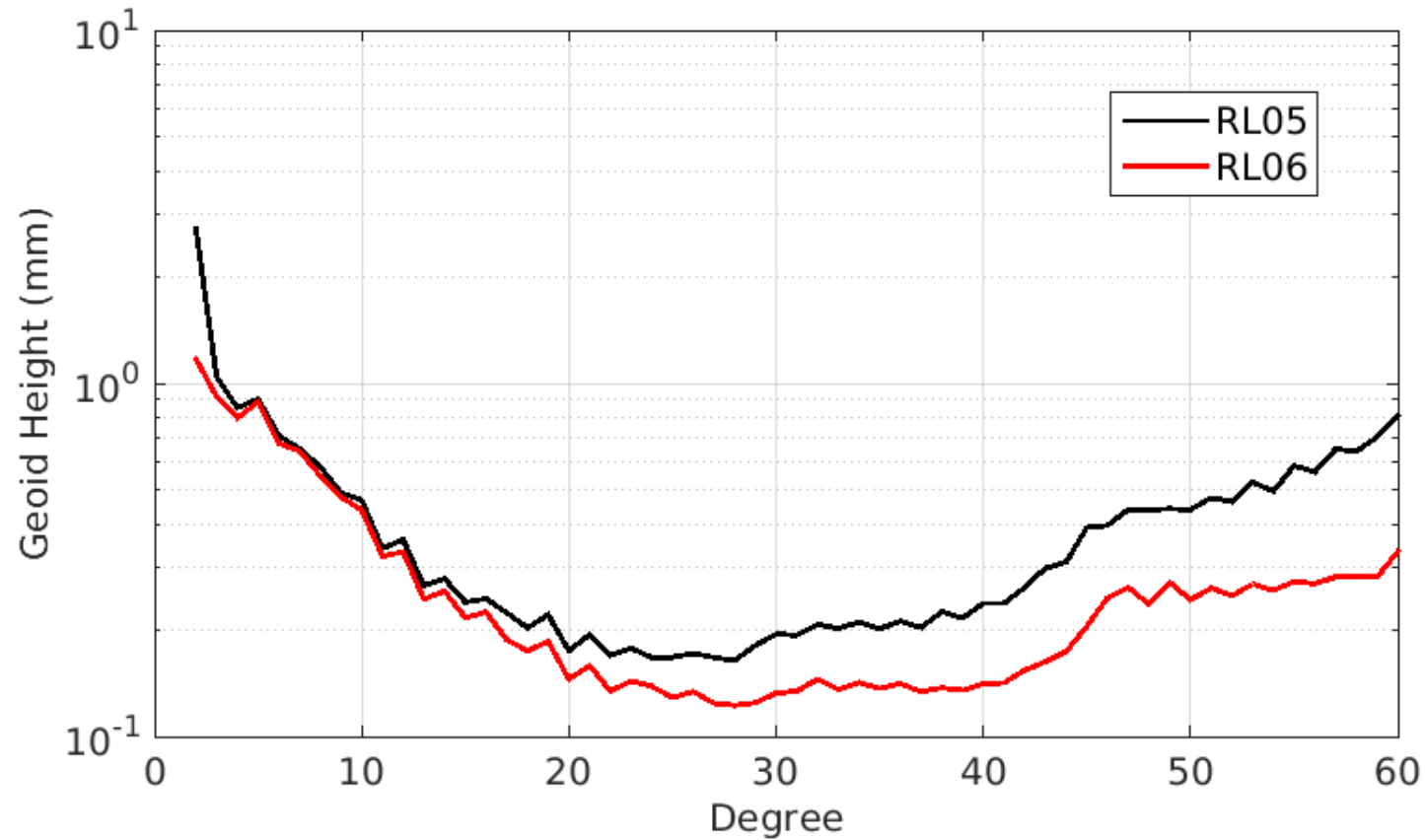
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Solution Quality: RL05 to RL06

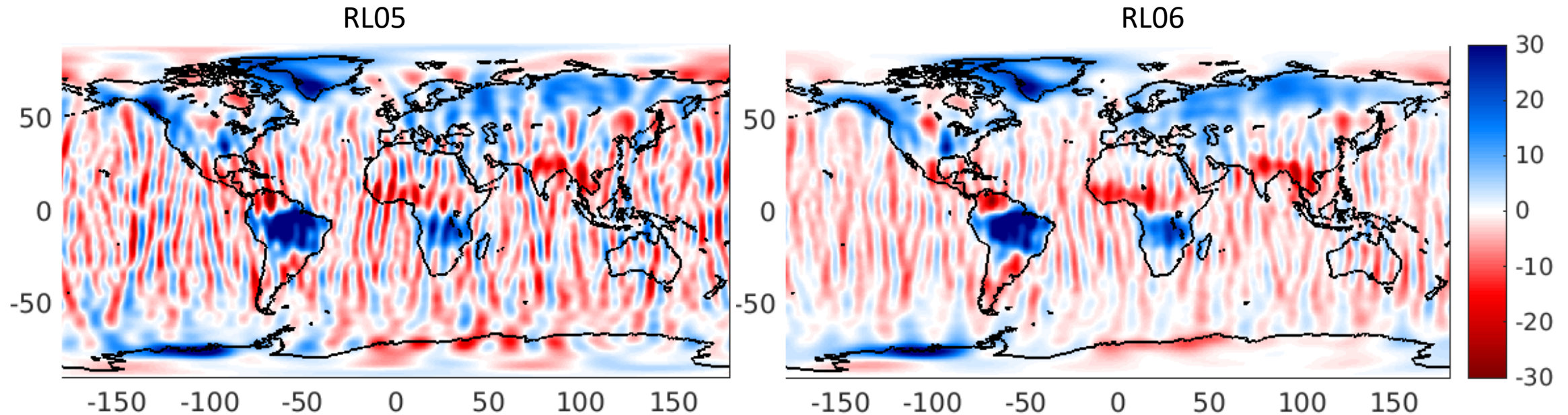


Average over all GRACE months



Solution Quality: RL05 to RL06

April 2008 with 300 km Gaussian smoothing

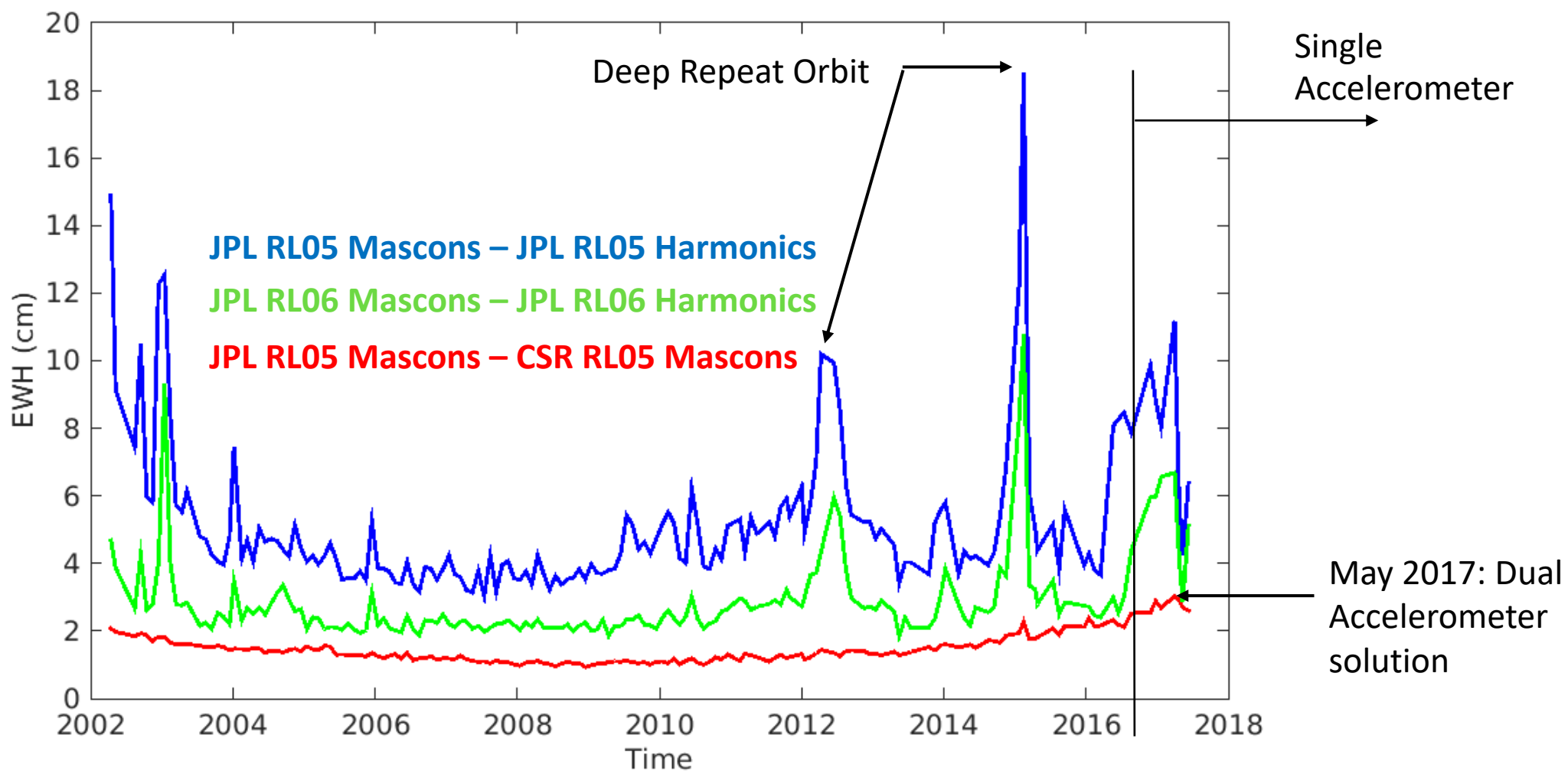


Solution Quality

GRACE / GRACE-FO



Global Spatial RMS of monthly differences between JPL Mascons: Smoothed at 300 km

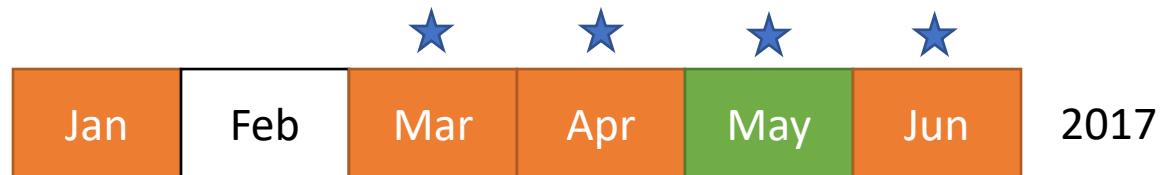


Single Accelerometer Months

Two accelerometer Solution

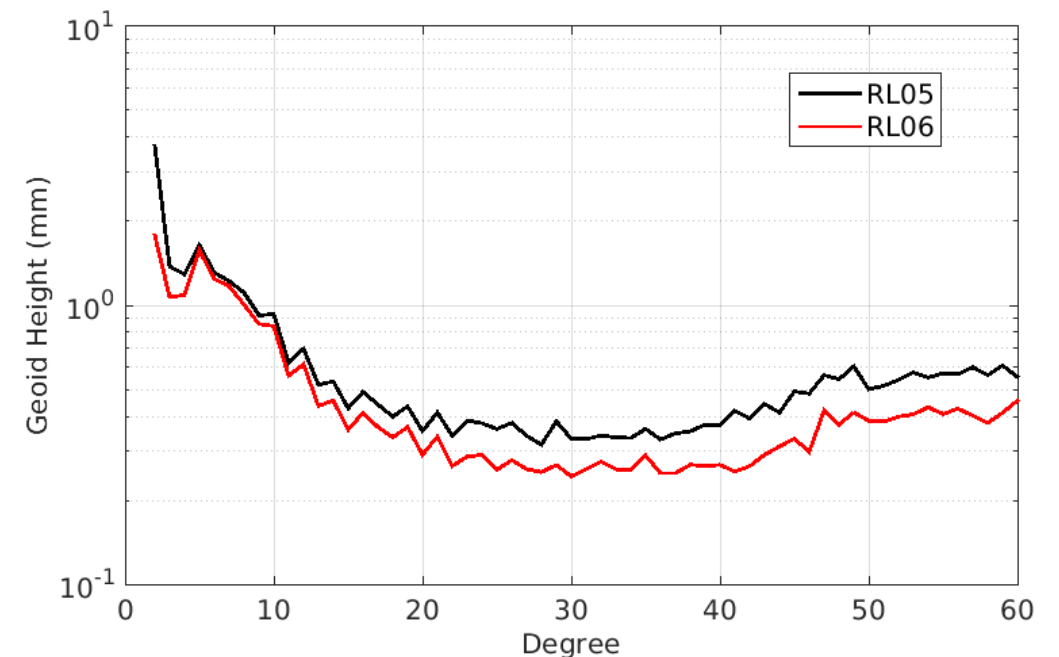
Single accelerometer Solution

★ Pitch Bias introduced



RL06 uses an improved accelerometer transplant from GRACE-A to GRACE-B which accounts for thruster firings on GRACE-B.
(Bandikova et al., in review)

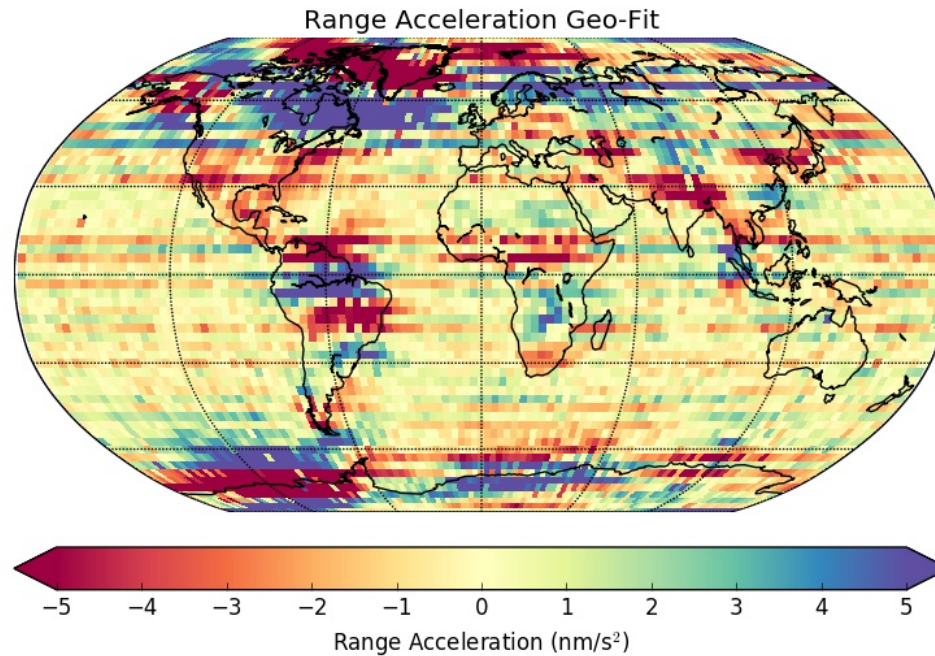
Average over single accelerometer months



Pitch Bias degradation is reduced (May 2017)

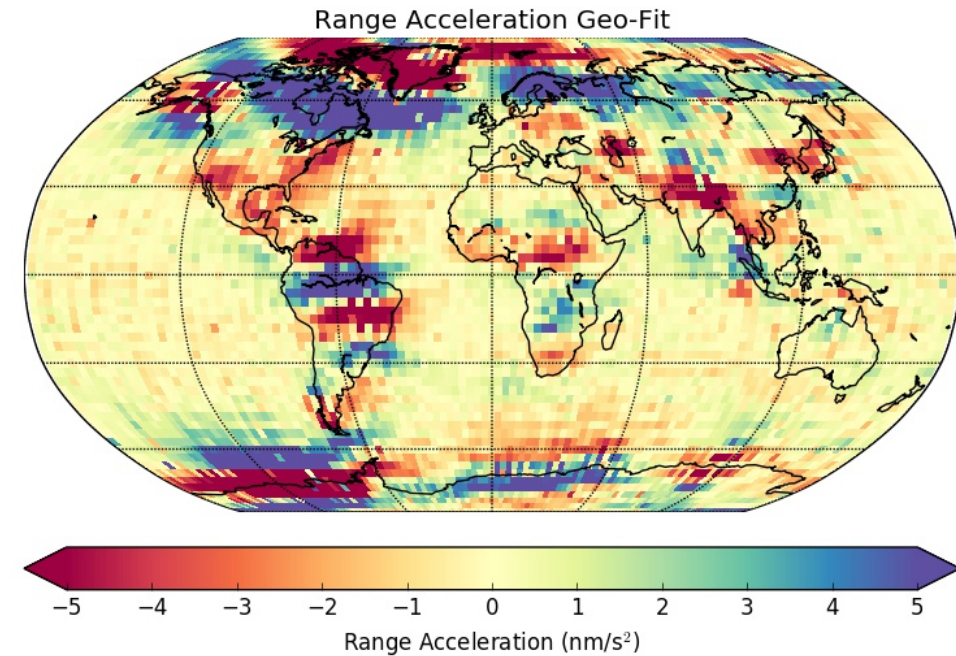
RL05: V02 Level-1 Data

Errors manifest in zonal harmonics leading to latitudinal banding in the gravity field



RL06: V03 Level-1 Data

Reduced high frequency noise in the attitude improves the solution



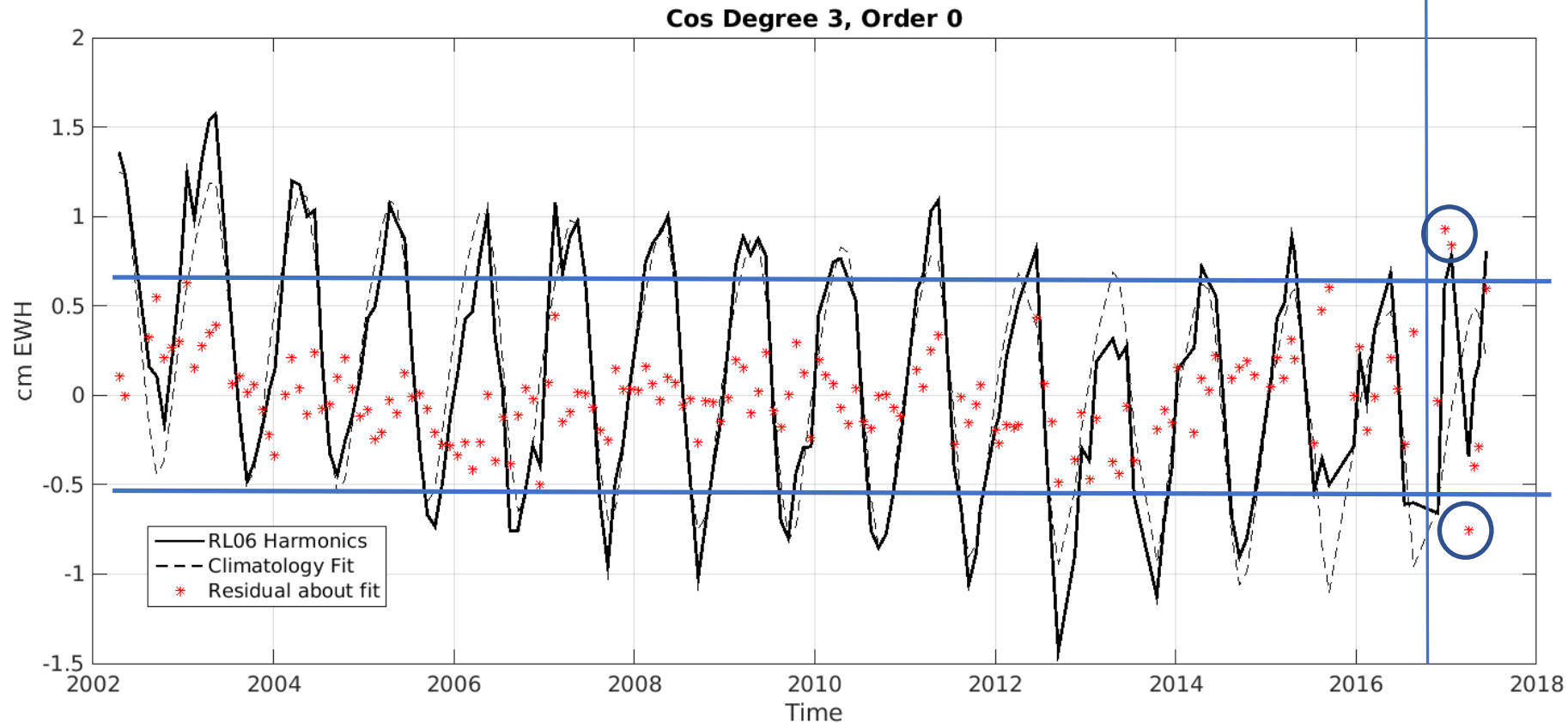
GEO-FIT plots: monthly gravity field correction mapped into range accelerations

Single Accelerometer – Low Degrees



Low degrees have improved in RL06, but still some problems with C_{30}

Single Accelerometer
→

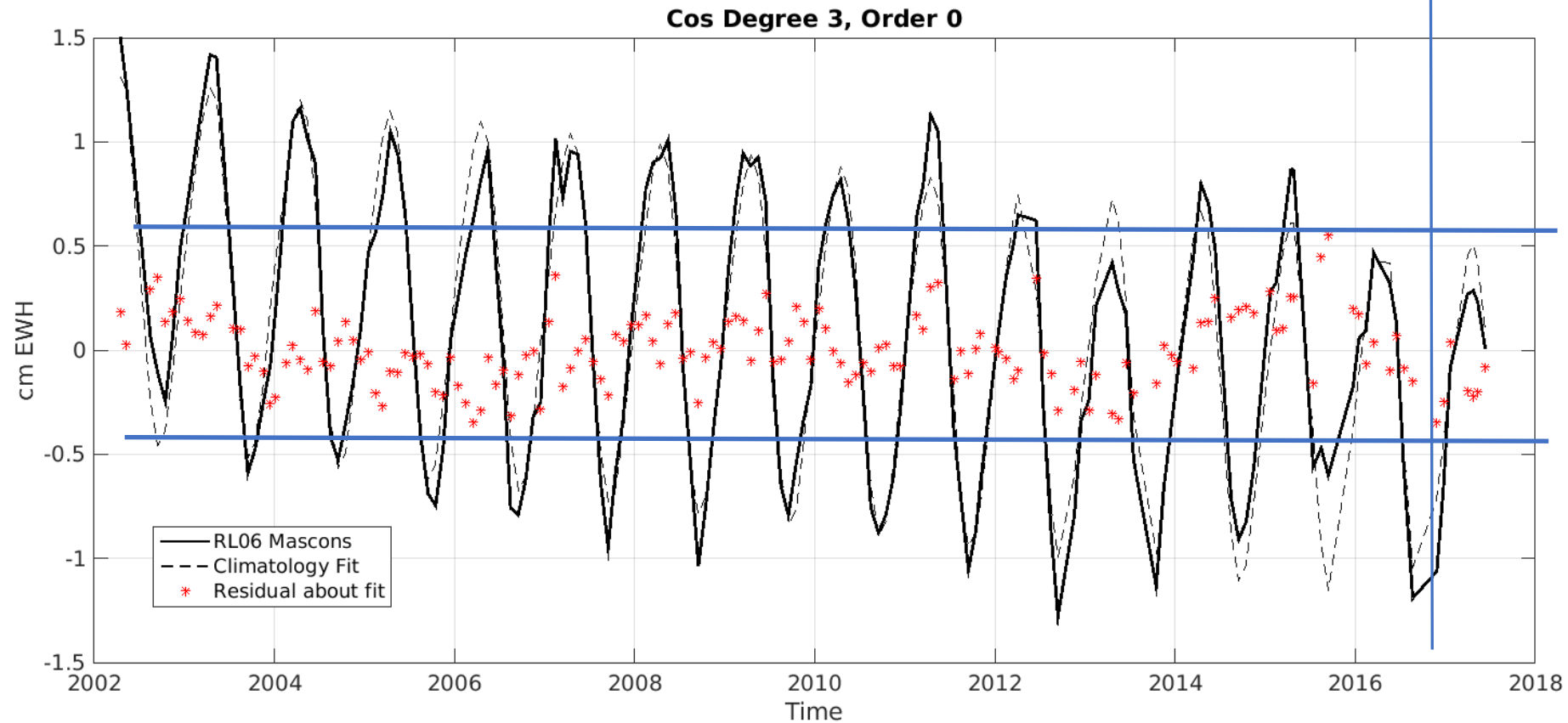


Single Accelerometer – Low Degrees



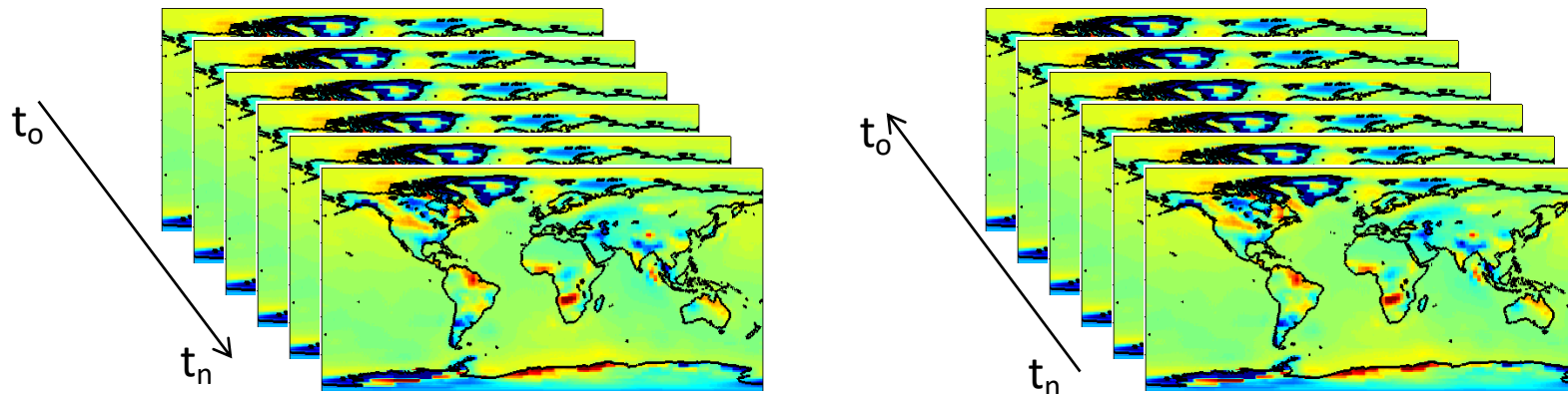
Low degrees, including C_{30} , are well behaved in mascon solution

Single Accelerometer



RL06 Mascon Strategy

- RL06 processing strategy is fundamentally the same as RL05 (*Watkins et al., 2015*)
- Improvements made
 - Addition of GPS normal equations
 - Full Accelerometer Scale Matrix is estimated daily
 - Change in the GIA forward model to ICE-6GD (*Peltier et al., 2017*)
 - Relaxation in initial conditions (apriori uncertainty) for time correlation run
 - Earthquake constraints have improved

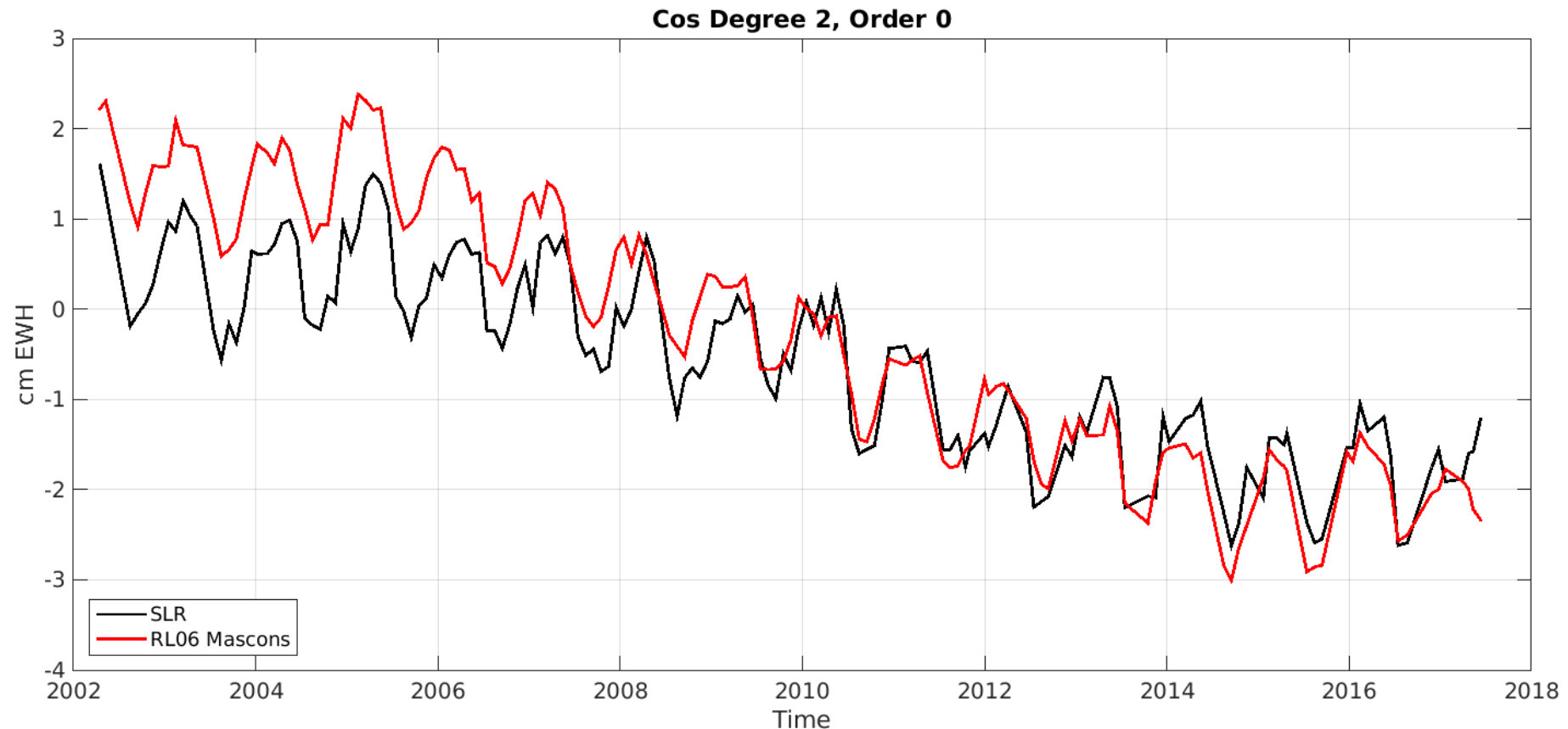


C_{20}

GRACE / GRACE-FO

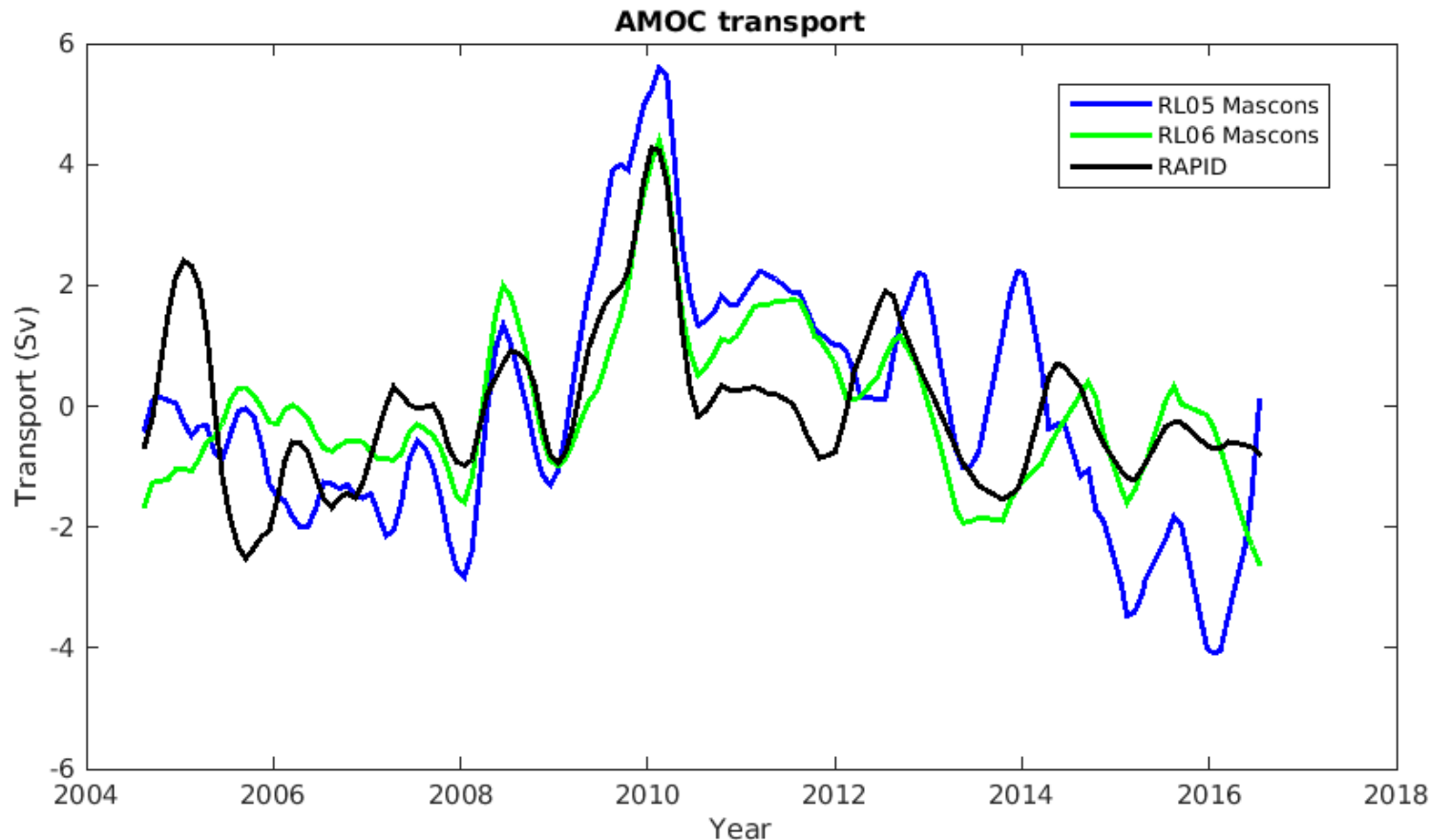


Mascons provide a “reasonable” estimate for C_{20} . The difference in trend with SLR (Cheng et al., 2013) is not well understood, however. We still replace the C_{20} coefficient with SLR values because of this.



Correlation with AMOC

We compare transport in the Lower North Atlantic Deep Water with the in-situ RAPID array using methods from *Landerer et al. (2015)*



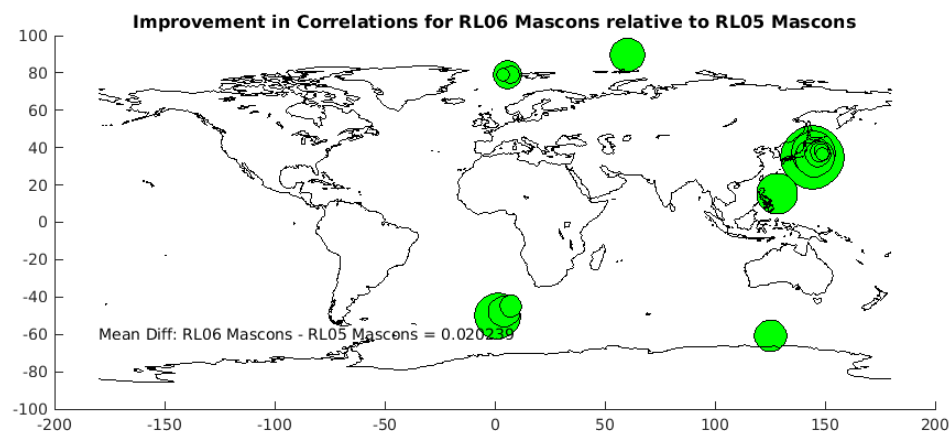
Correlation changes from
0.63 to 0.61

RMS relative to RAPID array
decreases from 1.58 Sv to
1.14 Sv.

Comparison with BPRs: RL05 vs RL06

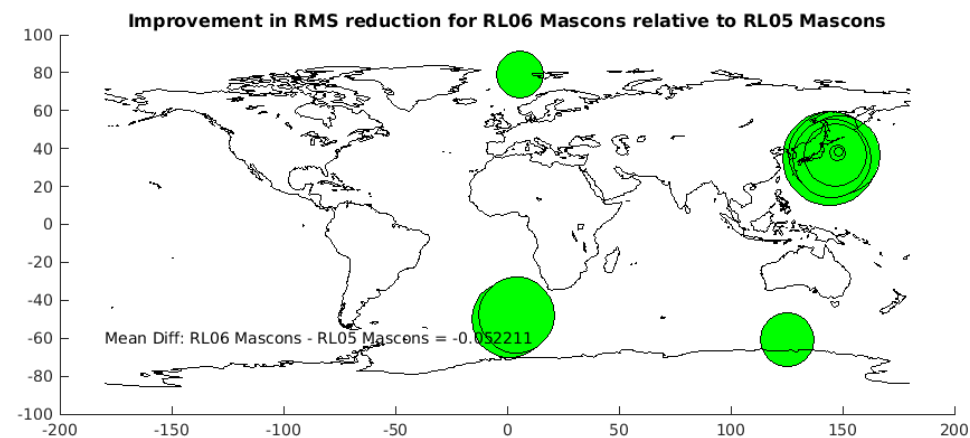
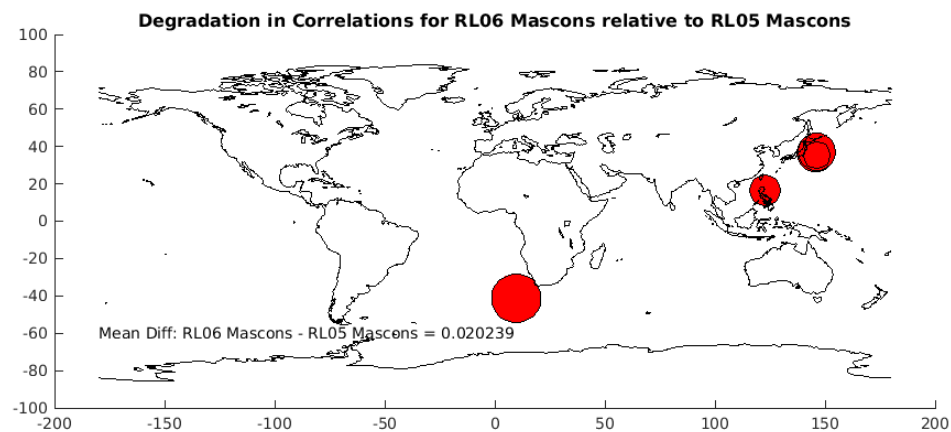
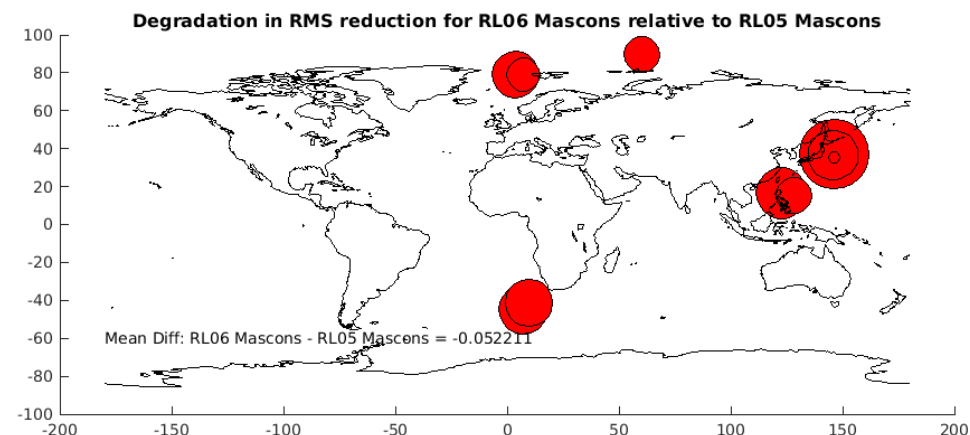
Correlation with in-situ data

Global improvement in correlation coefficient: 0.02



RMS relative to in-situ data

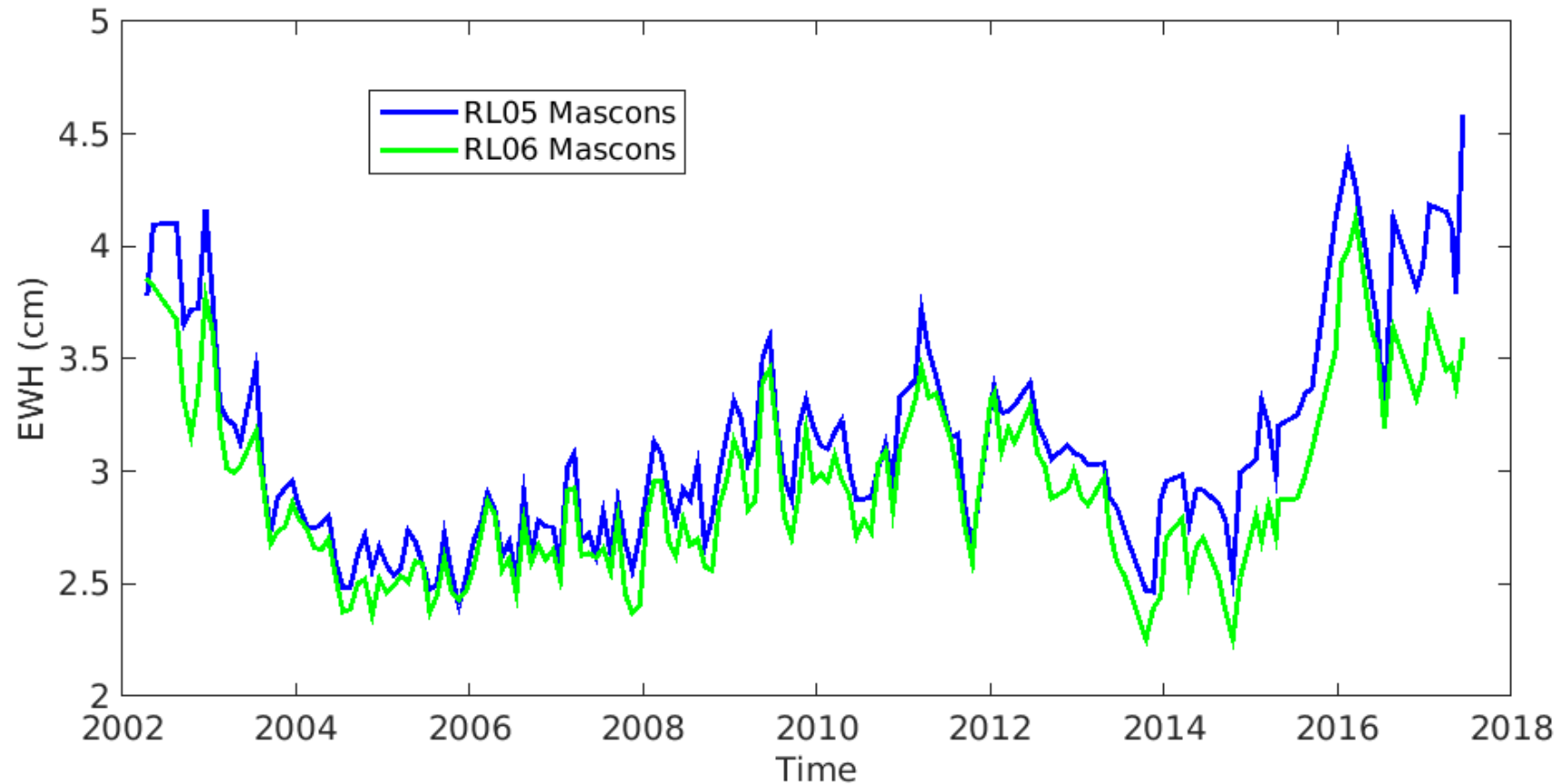
Global improvement in RMS reduction: 0.5 mm



RL05 vs RL06 Mascons

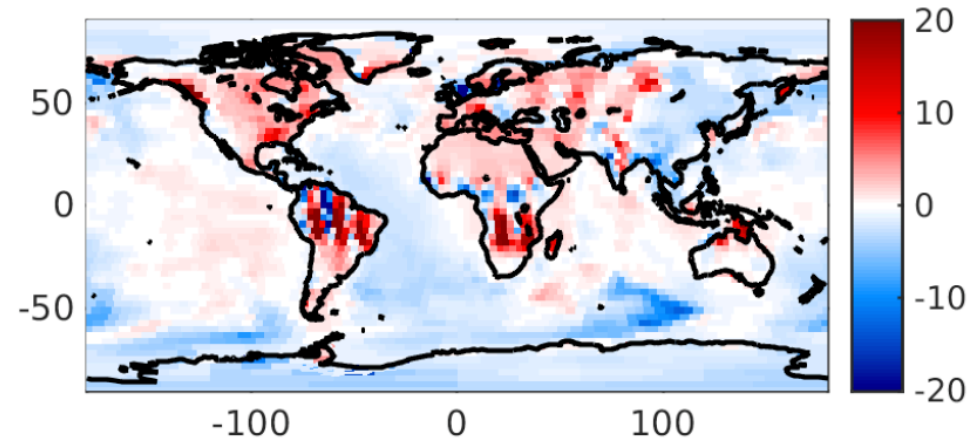
Monthly residuals about a climatology fit to the timeseries

We attribute the slight reduction in residuals in RL06 to a decrease in noise in the solution

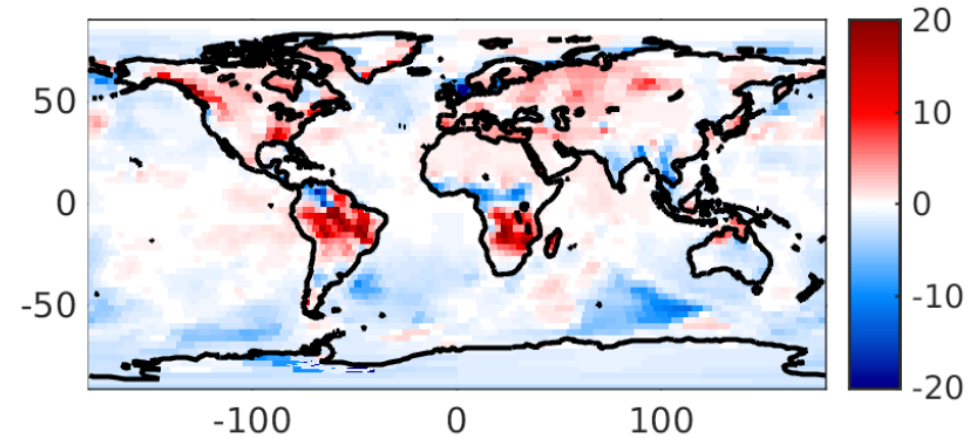


RL05 vs RL06 Mascons

RL05: Jan 2014 – Dec 2013



RL06: Jan 2014 – Dec 2013

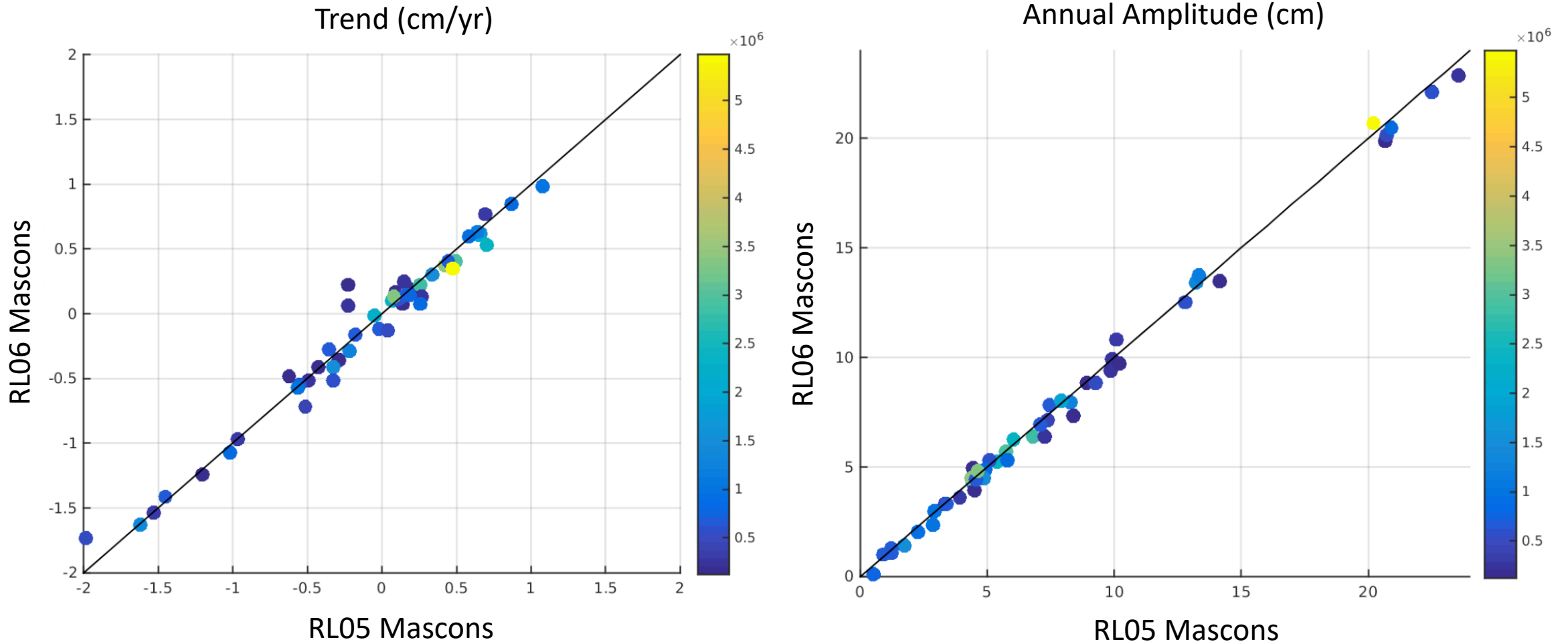


RL05 vs RL06 Mascons

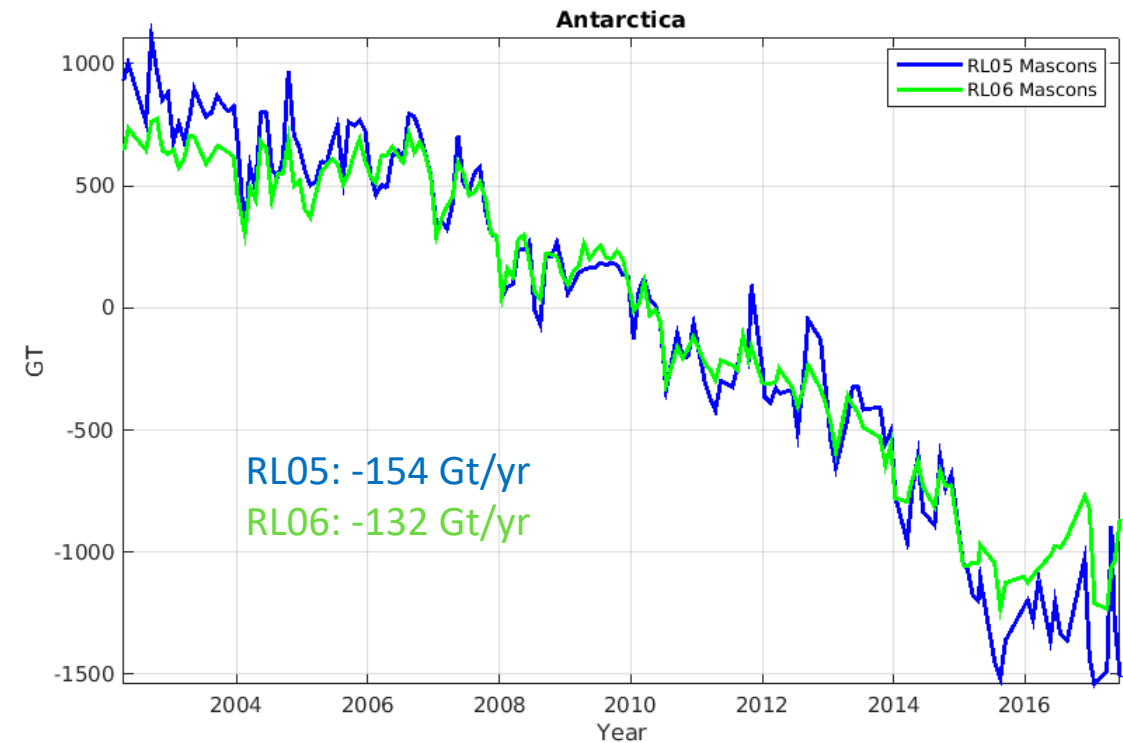
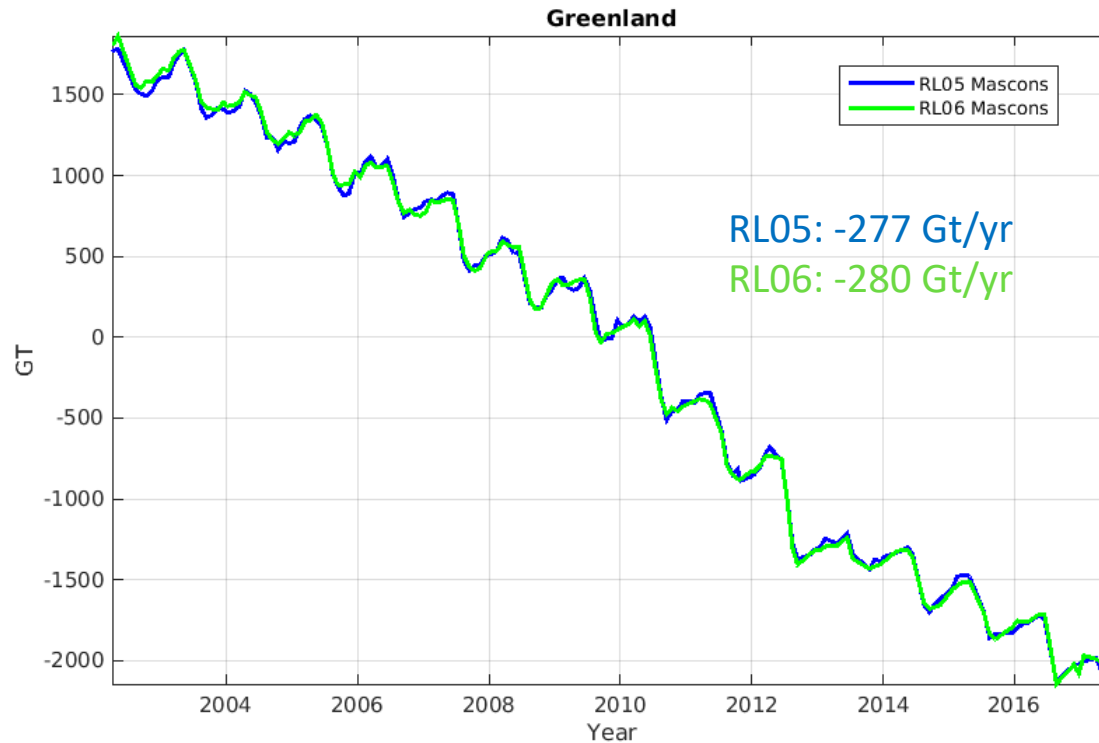
GRACE / GRACE-FO



Comparison over 50 hydrological basins

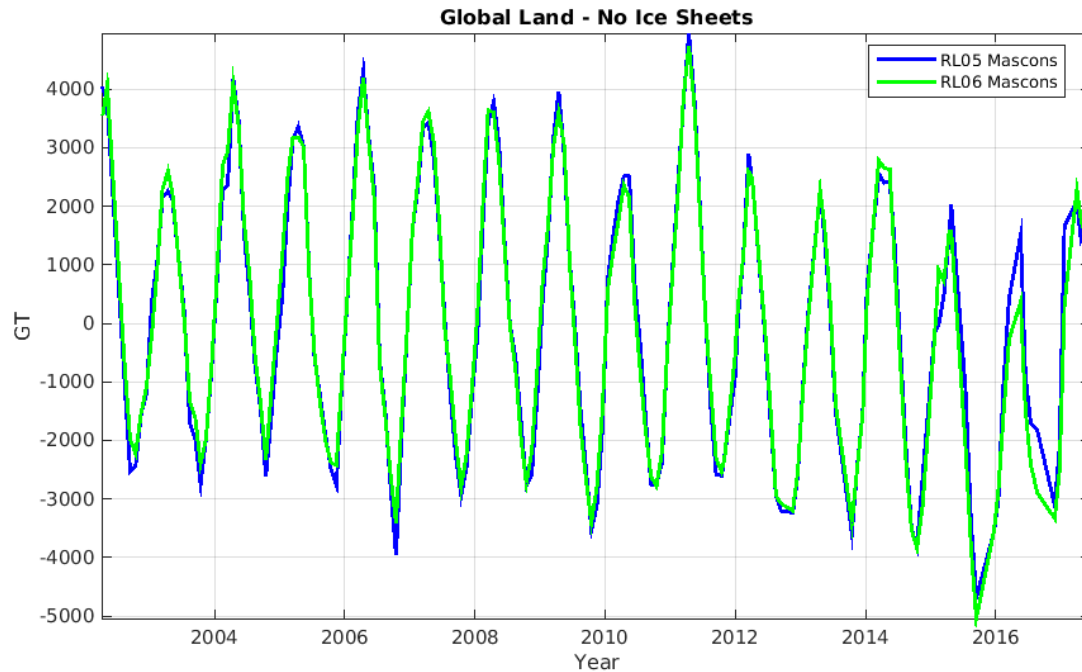


Ice Sheets: RL05 vs. RL06



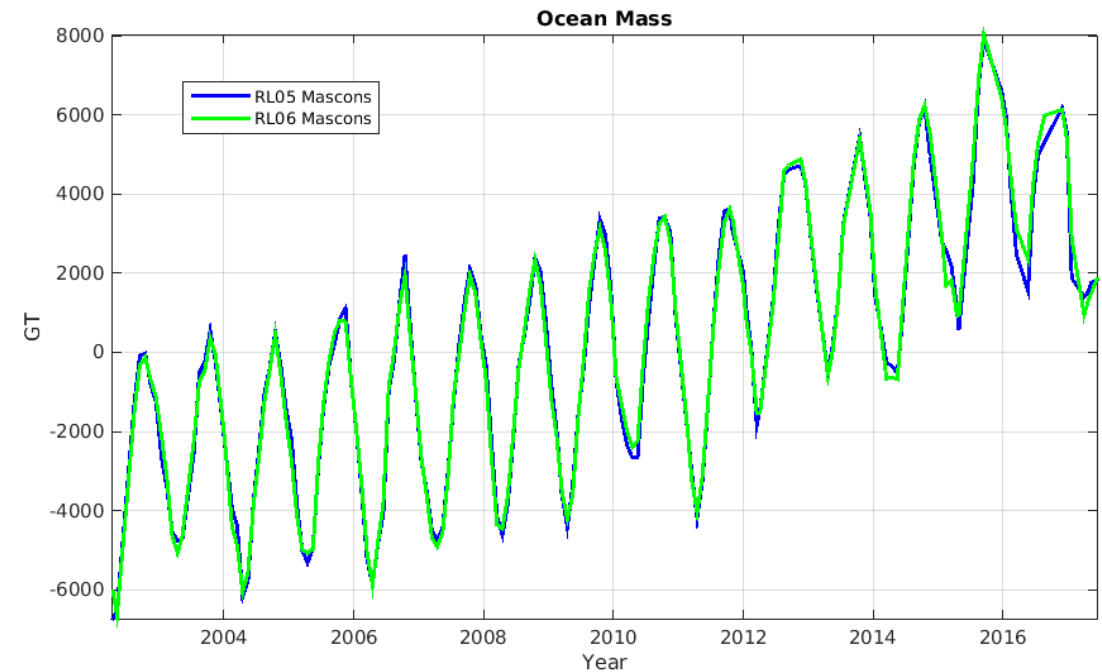
Note: RL05 implements *Wahr et al.* (2015) correction and AOD jump corrections (GAE, GAF, GAG). Both solutions remove ICE-6GD GIA.

Land/Ocean: RL05 vs. RL06



RL05: -0.33 mm SLE/yr

RL06: -0.42 mm SLE/yr



RL05: 1.59 mm SLE/yr

RL06: 1.62 mm SLE/yr

Note: RL05 implements *Wahr et al. (2015)* correction and AOD jump corrections (GAE, GAF, GAG). Both solutions remove ICE-6GD GIA.

Conclusions



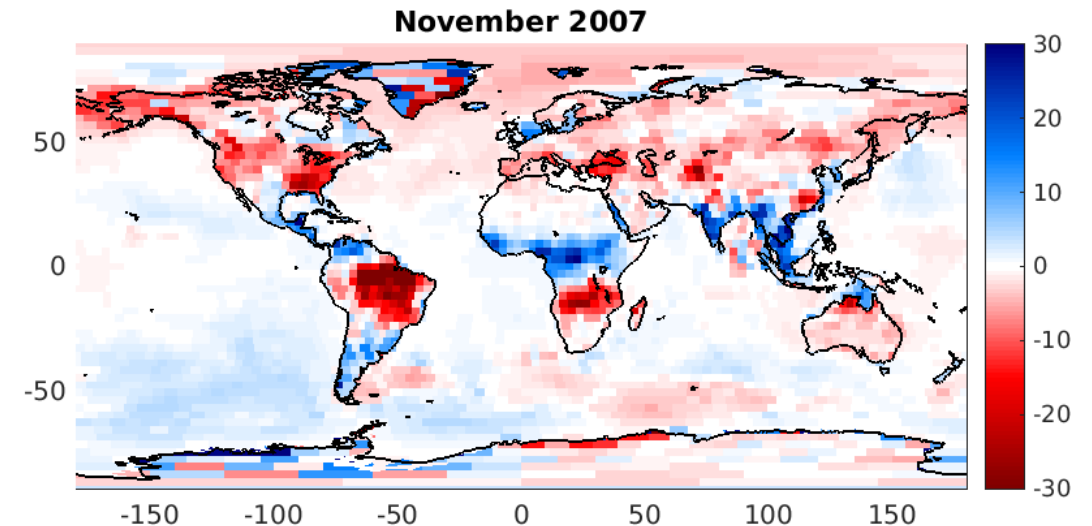
- JPL RL06 Data products for full GRACE data record will soon be available
- RL06 Unconstrained Harmonics represent a large improvement over RL05
 - Still some issues with low degree coefficients during single accelerometer months
- RL06 Mascons improve over RL05 Mascons
 - Better estimate of C_{20}
 - Improved agreement with AMOC LNADW transport
 - Reduction in residual noise in the solution
 - Reasonable estimates for low degree coefficients during single accelerometer months – this provides for better continuity with GRACE-FO

Backup

RL06 Mascons



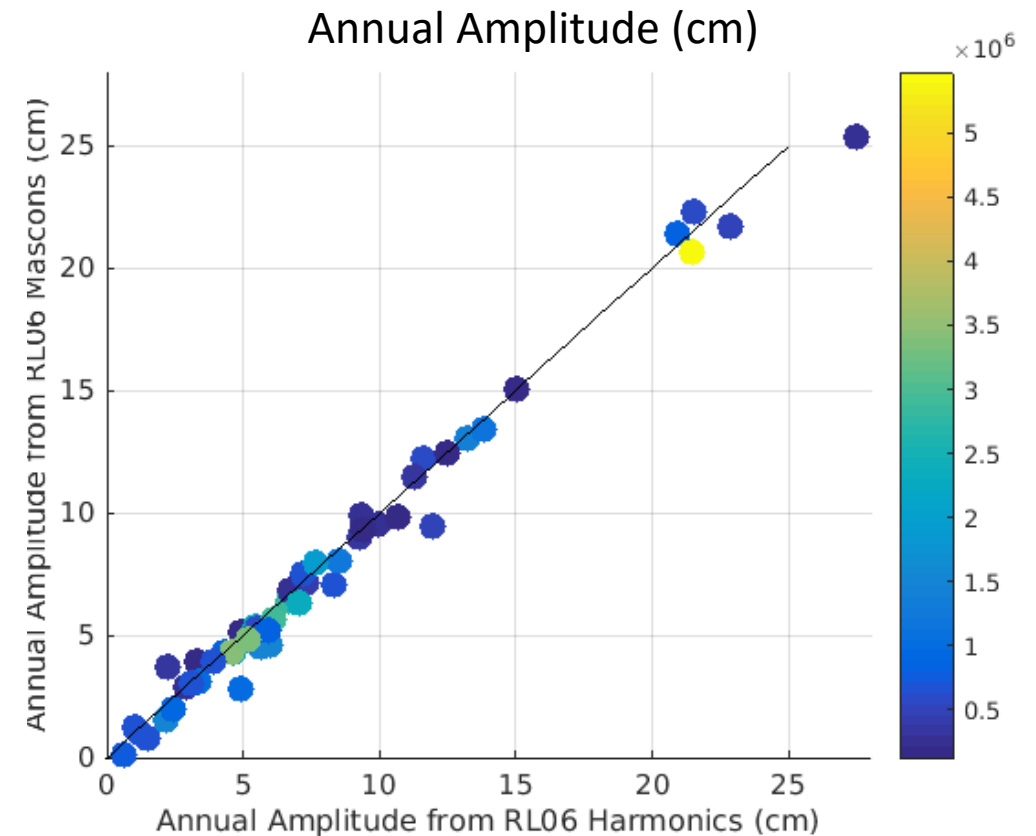
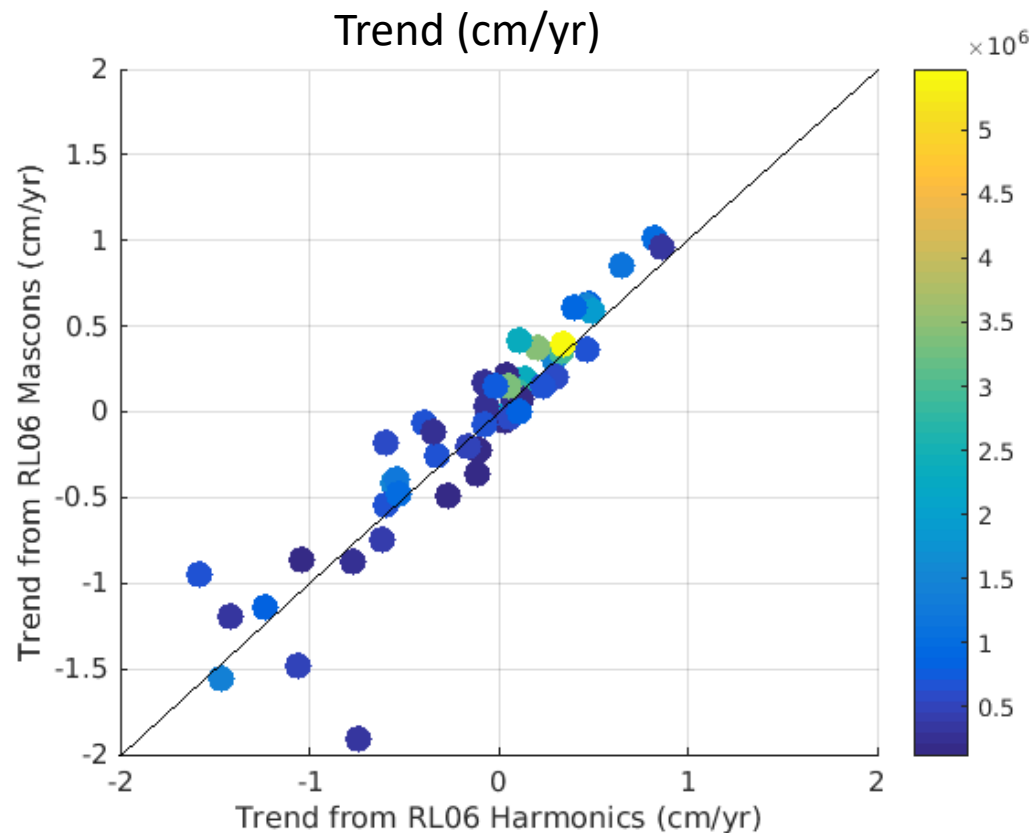
- Improved estimates of single accelerometer months
 - Low degree coefficients are much more reasonable
- Small reduction in noise relative to RL05
- Better estimate of C_{20}
 - SLR-replacement still recommended
- RL06 is very much “in family” with RL05
- Updated GIA correction: ICE-6GD (Peltier et al., 2018)



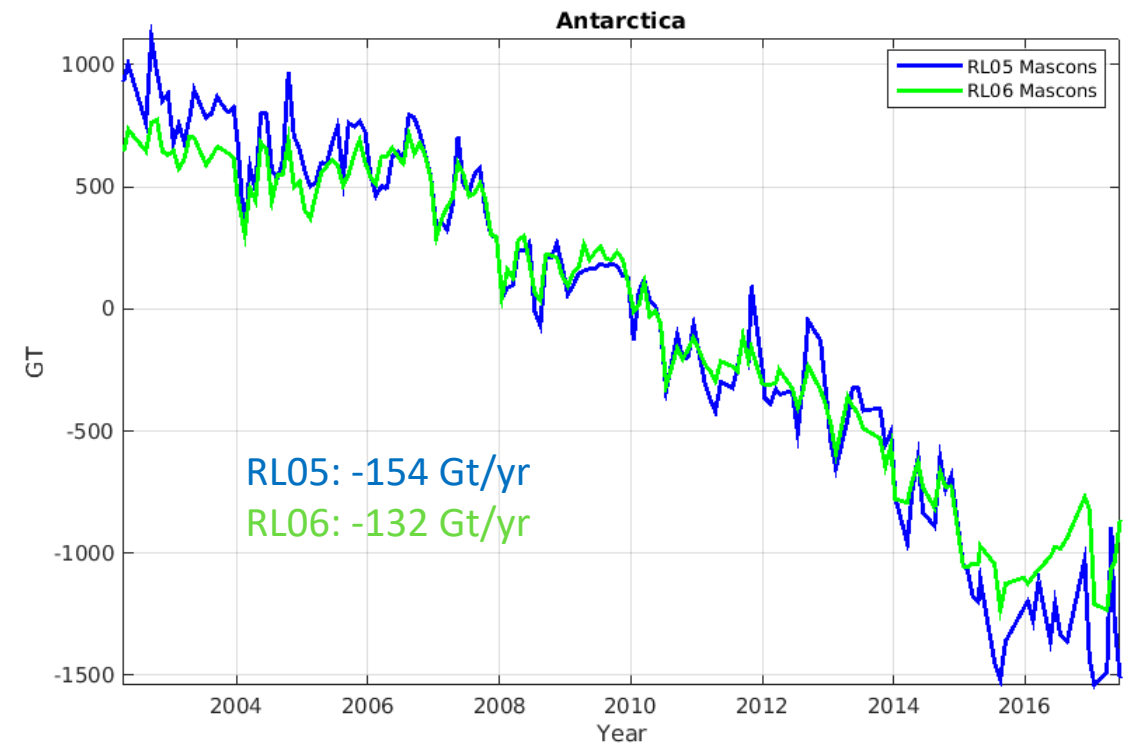
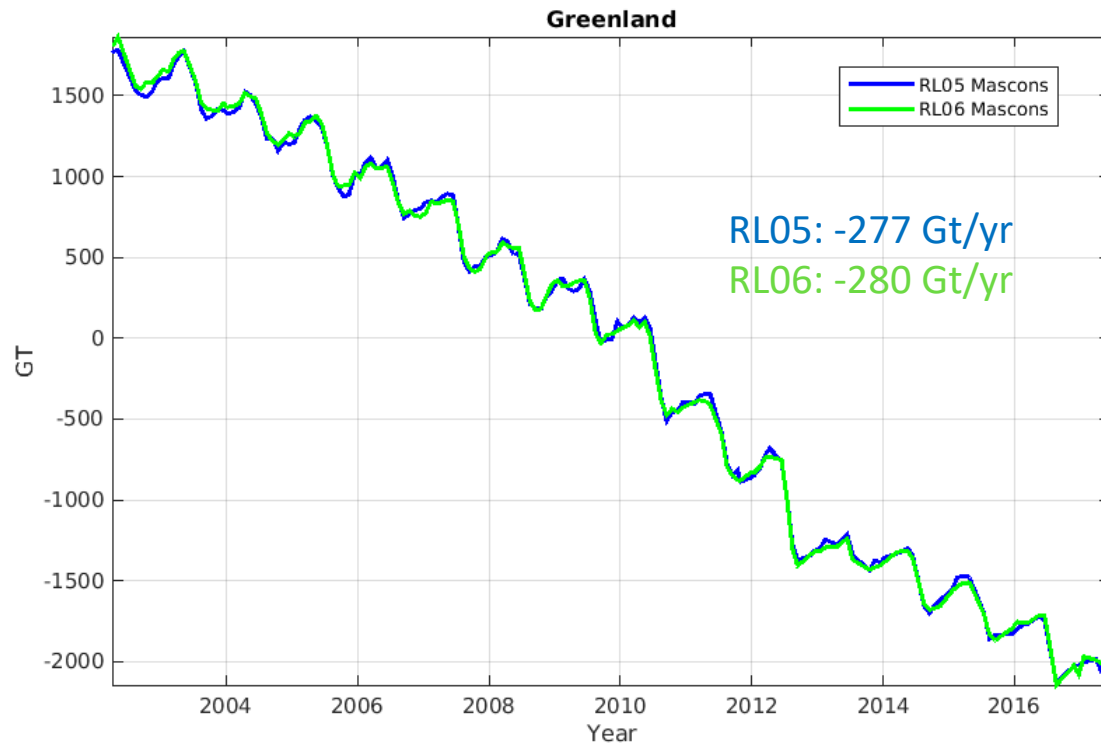
RL06 Mascons vs Harmonics

Comparison over 50 hydrological basins

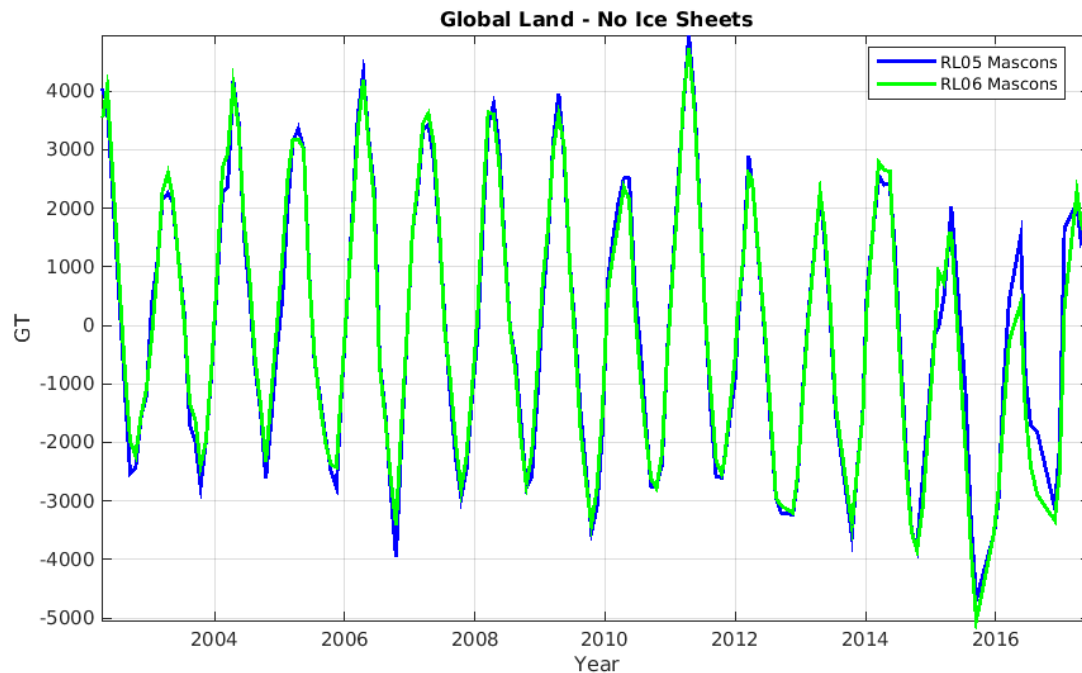
Harmonics have been destriped and smoothed (300 km), and scale factors applied to both solutions



Ice Sheets: RL05 vs. RL06

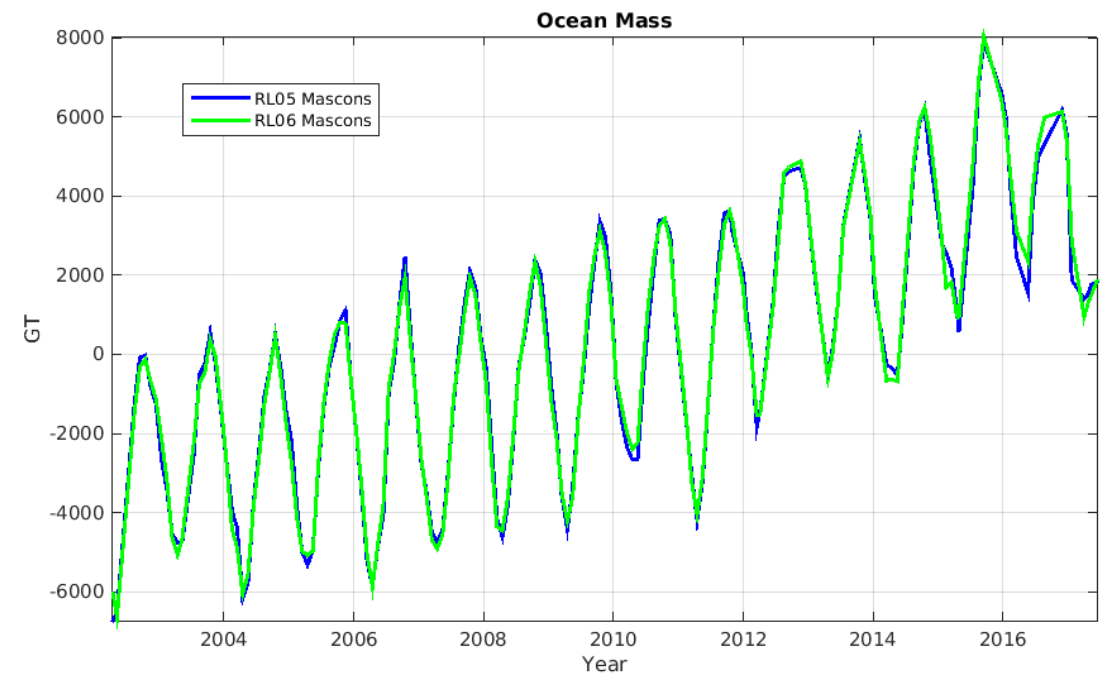


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